Mathematics and numerics for data assimilation and state estimation – Lecture 2



Summer semester 2020

Overview

1 Summary of lecture 1

2 Discrete random variables

- Independence of random variables and events
- Expected value and moments

3 Conditional probability and expectation

On ubungs, presentation and lectures

- 10:30-12:00 on most Fridays.
- Structure: 5-10 questions, which I will put up in pdf form on course webpage and on Moodle. Roughly 30 minutes work in groups or alone, where I will be present for discussions, thereafter solutions in plenary by me and/or you.
- No hand-ins, unless you want to (i.e., only for feedbac, kdoes not affect grade).
- The only "graded" part of the course, in the form of bonus points, is the presentation early July, and, of course, the final exam.
- Presentations can be done alone or in groups of maximum 2 people.
- Lectures after July 17th moved to first week of June.

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Measurable spaces and probability measures

- introduced a probabilty space $(\Omega, \mathcal{F}, \mathbb{P})$
- discrete random variable *X* : Ω → *A* = {*a*₁, *a*₂, . . . , } satisfies the event constraints

$$X^{-1}(a) = \{\omega \in \Omega \mid X(\omega) = a\} \in \mathcal{F} \quad ext{for all} \quad a \in A.$$

X can be represented by a simple function

$$X(\omega) = \sum_{a \in A} a \mathbb{1}_{X=a}(\omega).$$
 where $\mathbb{1}_{X=a}(\omega) := egin{cases} 1 & ext{if } X(\omega) = a \ 0 & ext{otherwise} \end{cases}$

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Discrete random variables 2

Example 1 (Coin toss, $X \sim \text{Bernoulli}(p)$) • image-space outcomes $A = \{0, 1\}$, • $\Omega = \{\text{Heads}, \text{Tails}\}, \quad \mathcal{F} = \{\emptyset, \{\text{Heads}\}, \{\text{Tails}\}, \Omega\}$ • X(Heads) = 1 and X(Tails) = 0 and $\mathbb{P}(X = 1) = \mathbb{P}(X^{-1}(1)) = \mathbb{P}(\text{Heads}) = p, \quad \mathbb{P}(X = 0) = \mathbb{P}(\text{Tails}) = 1 - p.$

Comment from last lecture: image-outcomes $\{a_1, a_2, \ldots, \}$ may not be associated uniquely to (probability-space) outcomes in Ω .

Larger set of outcomes in Ω than in A

Alternative, and admittedly confusing, probability space for the same rv as in the preceding example:

Example 2 (Coin toss, $X \sim \text{Bernoulli}(p)$)

- image-space outcomes $A = \{0, 1\} \subset \mathbb{R}$,
- $\Omega = \{ \textit{Heads}, \textit{Tails}, \textit{Nose} \}$ and

$$\begin{aligned} \mathcal{F} = \{ \emptyset, \{\textit{Nose}\}, \{\textit{Heads}\}, \{\textit{Tails}\}, \{\textit{Nose}, \textit{Heads}\}, \\ \{\textit{Nose}, \textit{Tails}\}, \{\textit{Heads}, \textit{Tails}\}, \Omega \} \end{aligned}$$

• $X^{-1}(1) = \{ Heads, Nose \}$ and $X^{-1}(0) = \{ Tails \}$ and

$$\mathbb{P}(X = 1) = \mathbb{P}(X^{-1}(1)) = \mathbb{P}(\{\text{Heads}, \text{Nose}\}) = p,$$

$$\mathbb{P}(X = 0) = \mathbb{P}(\text{Tails}) = 1 - p.$$

Motivation: if, for instance, you want to represent both a coin toss and a three-sided-die toss in the same probability space.

Joint rv 2201, 22, ... 3

If $X : \Omega \to A$ and $Y : \Omega \to B = \{b_1, b_2, \ldots\}$ are two discrete rv on the same probability space, then

■ (X, Y) : Ω → A × B is also a discrete rv with countable set of outcomes

$$A \times B = \{(a, b) \mid a \in A, b \in B\}.$$

with joint distribution:

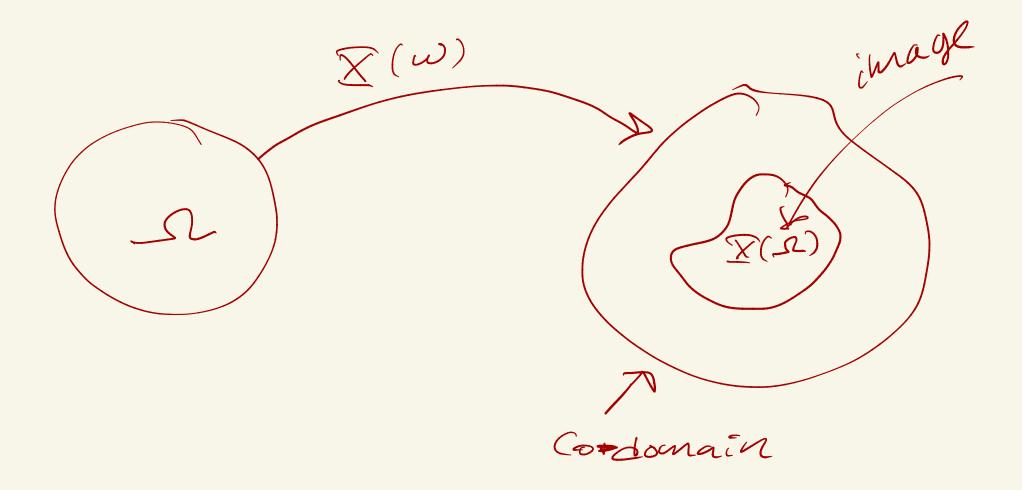
$$\mathbb{P}_{(X,Y)}((a,b)) = \mathbb{P}(X = a, Y = b).$$

Question: why is P(X = a, Y = b) defined? Answer: when we say X and Y are defined on the same probability space, this entails that

$$\{X = a\}, \{Y = b\} \in \mathcal{F} \underset{\text{since } \mathcal{F} \text{ is } \sigma-\text{algebra}}{\Longrightarrow} \{X = a\} \cap \{Y = b\} \in \mathcal{F},$$

and

$$\mathbb{P}(X = a, Y = b) = \mathbb{P}(\{X = a\} \cap \{Y = b\}).$$



•

Definition 3 (Independence of two rv)

If $X : \Omega \to A$ and $Y : \Omega \to B = \{b_1, b_2, \ldots\}$ are two discrete rv on the same probability space^a are said to be independent random variables if

$$\mathbb{P}(X = a, Y = b) = \mathbb{P}(X = a)\mathbb{P}(Y = b), \quad \forall a \in A \quad b \in B.$$

Notation: $X \perp Y$.

^aFrom now on, it will be implicitly assumed that all rv are defined on the same probability space, unless otherwise stated.

Example 4

Given independent coin tosses $X_k \sim Bernoulli(1/2)$ for k = 1, 2, describe the smallest possible σ -algebra on which the rv (X_1, X_2) is defined. **Solution:**

$$(X_{1}, X_{2})(\Omega) = \{(0,0), (1,0), (0,1), (1,1)\}$$

 $X^{-1}((0,0)), X^{-1}((1,0)), X^{-1}((1,1)) \in f$
and these events are disjoint

Suggestion $X^{-1}((0,0)) = \{Tails, Tails\} = \{TT\}$ $X^{-1}((1,0)) = \{ \text{Heads}, \text{Tails} \} = \{ \text{HT} \}$ X^{-((0,1))} = ZTails, Headsz = ZTHZ $X'((1,1)) = \{ \text{Heads}, \text{Heads} \} = \{ \text{HH} \}$ Answer: smallest o-algebra containing the above sets and D, and S. $f = \{\phi, \xi_{H}, \xi_{H}, \xi_{H}, \xi_{J}, \xi_{T}, \xi_{T}, \xi_{T}, \xi_{H}, \xi_{J}, \xi_{H}, \xi_{H}, \xi_{J}, \xi_{H}, \xi_{H},$ $\{HT, TH, TT3, \{HT, TT3, \{TH, TT3, \{HT, TH, TT3, \{HH, HT, TH, TT3, \{HH, HT, TT1, \{H, TT3, \{HT, TH, TT3, \{HT, TH, TT3, \{HT, TH, TT3, \{H, TT3, H, TT3, \{H, TT3, H, TT3, H,$

Example 5 (one coin toss and one three-sided-die toss)

- Consider $X : \Omega \to \{0, 1\}$ and and $Y : \Omega \to \{1, 2, 3\}$ both defined on the probability space from Example 2.
- Recall that $X^{-1}(1) = \{Heads, Nose\}$ and $X^{-1}(0) = \{Tails\}$ and let us assume that

$$\mathbb{P}(X = 1) = 1/2, \quad \mathbb{P}(X = 0) = 1/2$$



and that $Y^{-1}(1) = \{Heads\}, Y^{-1}(2) = \{Nose\}$ and $Y^{-1}(3) = \{Tails\}.$

• Quation: For p = 1/2, what is

$$\mathbb{P}(X=0,Y\in\{1,2\})=\iint\{\mathcal{F}_{a}\mid \mathcal{F}_{a}\mid \mathcal{F}$$

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■ Question: Are X and Y independent?

 $X \perp T \Leftrightarrow P(X=a, Y=b) = P(X=a)P(X=b)$ on the one hand $P(X=0, Y \in \{1,2\}) = 0$ on the other $P(X=0) P(Y \in \{1,2\}) = P(Tails) P(\{teals, Ns])$ $=\frac{1}{4}$ P(Z=0, TEZ1,23) + RX-0) R(ZEZ1,23) >> XXXX

Independence of multiple rv

Definition 6

Let $X_k : \Omega \to A_k$ for k = 1, 2, ..., N, be a finite sequence of discrete rv. Then $X_1, X_2, ..., X_N$ are independent provided

$$\mathbb{P}(X_1 = a_1, X_2 = a_2, \dots, X_N = a_N) = \prod_{k=1}^N \mathbb{P}(X_k = a_k)$$
(1)

for all $a_1 \in A_1$, $a_2 \in A_2$, ..., $a_n \in A_N$. Extension: A **countable** sequence of discrete rv $X_1, X_2, ...$ are independent provided every finite subsequence $\{X_{k_i}\}_i$ satisfies (1).

XK=SL >AK= EO, B

Example 7

Let $X_i \sim Bernoulli(p)$ for i = 1, ..., N with joint distribution

$$\mathbb{P}\left(X_{1}=a_{1},X_{2}=a_{2},\ldots,X_{N}=a_{N}
ight)=p^{\sum_{k=1}^{N}a_{k}}(1-p)^{N-\sum_{k=1}^{N}a_{k}}$$

for any $a_1, \ldots, a_N \in \{0, 1\}$. Then X_1, X_2, \ldots are independent and identically distributed (iid).

$$(f) P(X_{k} = a_{k}) = P^{a_{k}}(1-P)^{1-a_{k}} \text{ for } k=1,...,N$$

$$= P(X_{i}=a_{i},...,X_{N}=a_{N}) = \prod_{k=1}^{n} P(X_{ik}=a_{k})$$

Example 8 (Functions of joint discrete rv are also discrete rv) Let $X_i \sim Bernoulli(p)$ be independent for i = 1, 2, ..., N and

$$S_N = f(X_1,\ldots,X_N) := \sum_{i=1}^N X_i.$$

Then

$$\mathbb{P}(S_N = k) = \binom{N}{k}(1-p)^{N-k}p^k$$

 S_N is called the **Binomial distribution** with degrees of freedom N and p, and we write $S_N \sim B(N, p)$.

Comment: the number of different ways the event $\{S_N = k\}$ when flipping N independent coins once equals factor in the k + 1-th summand of

$$((1-p)+p)^{N} = (1-p)^{N} + {N \choose 1} p(1-p)^{N-1} + \ldots + {N \choose k} p^{k} (1-p)^{N-k} + \ldots$$

Independence of events

Equation (1) is on the form:

$$\mathbb{P}\left(\bigcap_{k=1}^{N} \{X_k = a_k\}\right) = \mathbb{P}(\text{intersection of events}) = \text{Product of}\left[\mathbb{P}(\text{each event})\right]$$

Definition 9

A finite sequence of events H_1, H_2, \ldots, H_N that belongs to \mathcal{F} are independent provided

$$\mathbb{P}\left(\bigcap_{k=1}^{N}H_{k}\right)=\prod_{k=1}^{N}\mathbb{P}(H_{k})$$
(2)

A **countable** sequence of events A_1, A_2 , belonging to \mathcal{F} are independent provided finite subsequence $\{A_{k_i}\}_j$ satisfies (2).

Connection between independence of rv and independence of events $\underbrace{\Pi}_{H_2} \perp \underbrace{\Pi}_{H_2} \Leftrightarrow R \left(I_{H_1} = a_1 \underbrace{\Pi}_{H_2} = b \right) = R \left(I_{H_1} = a_1 R_{H_2} = b \right) = R \left($

Given a probability space $(\Omega, \mathcal{F}, \mathbb{P})$, we can assign an rv to each event $H \in \mathcal{F}$ as follows

$$\mathbb{1}_{H}(\omega) := egin{cases} 1 & \omega \in H \ 0 & ext{otherwise} \end{cases}$$

Easy consequence of preceding definition: $\mathbb{1}_{H_1}$ and $\mathbb{1}_{H_2}$ are independent if and only if

$$\mathbb{P}(H_1 \cap H_2) = \mathbb{P}(H_1)\mathbb{P}(H_2).$$

$$\mathbb{I}_{H} : \mathcal{D} \rightarrow \{o, I\}$$

$$\mathbb{I}_{H} : (o) = H^{c} \in \mathcal{F} \qquad \mathbb{I}_{4}^{-1}(1) = H \in \mathcal{F}$$

$$\mathbb{I}_{H} \sim \mathbb{Bernoulli}(\mathbb{P}(\mathcal{H}))$$

Expectation of rv

Definition 10

For a discrete rv $X:\Omega
ightarrow A\subset \mathbb{R}^d$, the expectation X is defined as

$$\mathbb{E}[X] := \int_{\Omega} X(\omega) \mathbb{P}(d\omega) = \sum_{a \in A} a \mathbb{P}(X = a)$$

Motivation of the above integral: $\int_{\Omega} X(\omega) \mathbb{P}(d\omega) = \int_{\Omega} \sum_{a \in A} \alpha \prod_{\substack{\{\omega\} \in A}} (\omega) \mathbb{P}(d\omega)$ The condition $= \sum_{a \in A} \alpha \int_{\Omega} \frac{1}{X = \alpha} \mathbb{P}(d\omega) = \dots$ $\mathbb{E}[|X|] = \sum_{a \in A} |a| \mathbb{P}(X = a) < \infty$

is a sufficent condition for $\mathbb{E}[X]$ being defined and bounded.

 $\mathbb{E}[X] = \mathcal{O} \cdot \mathcal{R}(\mathbb{Z} = \mathcal{O}) + \mathcal{I} \cdot \mathcal{R}(\mathbb{Z} = \mathcal{I}) = \mathcal{O} \cdot (\mathcal{I} - \mathcal{P}) \\ + \mathcal{I} \cdot \mathcal{R} = \mathcal{P}$

 $= \sum_{\alpha \in A} a \int \frac{1}{X} (\omega) P(d\omega) \\ = a P(d\omega)$

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= 5 a P(X=a)GeA

Expectation of rv

Definition 11

For a discrete rv $X:\Omega
ightarrow A\subset \mathbb{R}^d$, the expectation X is defined as

$$\mathbb{E}[X] := \int_{\Omega} X(\omega) \mathbb{P}(d\omega) = \sum_{a \in A} a \mathbb{P}(X = a)$$

The condition

$$\mathbb{E}[|X|] = \sum_{a \in A} |a| \mathbb{P}(X = a) < \infty$$

is a sufficent condition for $\mathbb{E}[X]$ being defined and bounded.

For mappings $f : \mathbb{R}^d \to \mathbb{R}^k$ and rv f(X) the above definition readily extends:

$$\mathbb{E}[f(X)] = \sum_{a \in A} f(a)\mathbb{P}(X = a).$$

$$\mathbb{E}[X] = \mathbb{E}[X] = \mathbb{E}[X] = \mathbb{E}[X] = \mathbb{E}[X] = \mathbb{E}[X] = \mathbb{E}[X]$$

Properties of the expectation

For mappings $f : \mathbb{R}^d \to \mathbb{R}^k$ and rv f(X), the expectation becomes

$$\mathbb{E}[f(X)] = \sum_{a \in A} f(a) \mathbb{P} (X = a).$$

• For a pair of rv $X : \Omega \to A \subset \mathbb{R}^d$ and $Y : \Omega \to B \subset \mathbb{R}^d$, it holds for any $c \in \mathbb{R}$, that

$$\mathbb{E}[X+cY] = \mathbb{E}[X] + c \mathbb{E}[Y]$$

provided $\mathbb{E}[|X|] + \mathbb{E}[|Y|] < \infty$ (sufficient condition).

Motivation:

$$\int \mathbf{X}(\omega) + c \mathbf{Y}(\omega) \, \mathbf{P}(d\omega) = \int \mathbf{X}(\omega) \, \mathbf{P}(d\omega) + c \int_{\Sigma} \mathbf{Y}(\omega) \, \mathbf{P}(d\omega) + c \int_{\Sigma} \mathbf{Y}(\omega) \, \mathbf{P}(d\omega)$$

Properties of the expectation 2

Probability of events can be expressed through expectations:

$$\mathbb{P}(H) = \int_{H} \mathcal{P}(\mathcal{A}w) = \int_{\mathcal{T}} I_{H}(\omega) \mathcal{P}(\mathcal{A}w) = \mathbb{E}[\mathbb{1}_{H}]$$

for any $H \in \mathcal{F}$.

• Expectation of discrete rv of the form f(X, Y) where $X : \Omega \to A$ and $Y : \Omega \to B$:

$$\mathbb{E}[f(X,Y)] = \sum_{a \in A, b \in B} f(u,b) \left(\mathbb{R}(X=a, Y=b) \right)$$

Variance of an rv

• For
$$X: \Omega \to A \subset \mathbb{R}$$

$$F(k) = \mathbb{E}[(X-k)^2]$$

is the squared deviation of X from k in expectation.

For $\mu:=\mathbb{E}[X]$, and provided $\mathbb{E}[X^2]<\infty$, it can be shown that

$$F(k) = \left(\mathbb{E} \left[(X - k)^2 \right] = \left(\mathbb{E} \left[(X - k)^2 \right] + 2(k - k) \mathbb{E} \left[(X - k) + (k - k) \right]^2 \right]$$

=
$$\left(\mathbb{E} \left[(X - k)^2 \right] + 2(k - k) \mathbb{E} \left[(X - k)^2 \right] + (k - k)^2 = \cdots \right]$$

Which motivates the variance of X:

$$Var(X) := \mathbb{E} \left[(X - \mu)^2 \right] \qquad \text{(out next}$$

• For $X \sim Bernolli(p)$, $\mu = p$ and

$$Var(X) =$$

Observe that $\left| E \left[E - \mu \right] = \mu - \mu = 0$ $= = E\left[\left(x - \mu\right)^{2}\right] + O + \left(\mu - \kappa\right)^{2}$ $= F(\kappa)$ $E[(X-K)^2] = E[(X-m)^2] + (ve-k)^2$ Z(E[X-M]] = F(M)

 $Var(X) = (E(X-m)^{2})^{2} = \sum_{n=1}^{\infty} (a-m)^{2} ll(X=a)$ $X \cap Bernouelli(P), E[X] = P$ $Var(X) = (O-P)P(X=0) + (I-P)P(X=1) = P^{2}(I-P) + (I-P)P$ = P(I-P)

Notation with same meaning

For events $H_1, H_2, \ldots \in \mathcal{F}$, the following notation is used interchangeably in the literature

$$\mathbb{P}(H_{1}H_{2}\ldots H_{n}) = \mathbb{P}(H_{1}, H_{2}, \ldots, H_{n}) = \mathbb{P}\left(\bigcap_{j=1}^{n} H_{j}\right).$$
And since
$$\mathbb{1}_{\bigcap_{j=1}^{n} H_{j}} = \prod_{i=1}^{n} \mathbb{1}_{H_{j}}.$$
we have that
$$\mathbb{P}\left(\bigcap_{j=1}^{n} H_{j}\right) = \mathbb{E}[\mathbb{1}_{\bigcap_{j=1}^{n} H_{j}}] = \mathbb{E}[\prod_{i=1}^{n} \mathbb{1}_{H_{j}}]$$

 $\mathbb{P}(\hat{U}_{j=1}, \mathcal{H}_{j}) \leq \mathbb{E}[\tilde{\Sigma}_{j=1}, \mathcal{H}_{j}]$